

Higher Dimensional Timed Automata

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Uli Fahrbenberg

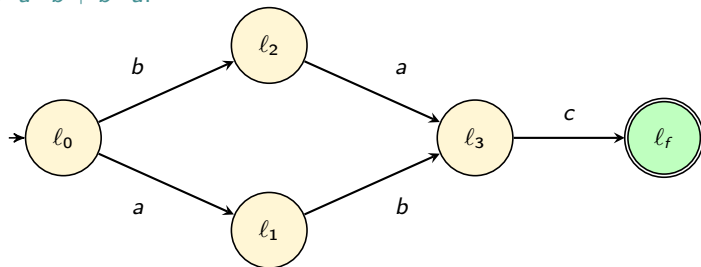


Amazigh Amrane



Hugo Bazille

- $a \cdot b + b \cdot a$:



- Goal of HDA

Represent several events $a, b, c \dots$ and their order

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Simple case: a and b can occur in parallel

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Or.. a can **begin** before b does and a can **end** before b does ...

While c happens before the end of b and a !

How to represent n -ary parallel events? Ipomset

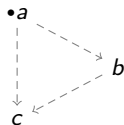
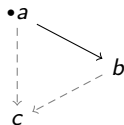
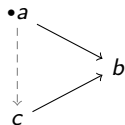
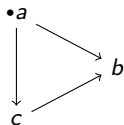
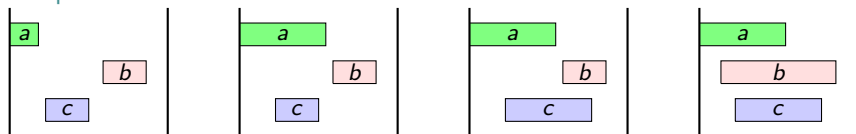
- Two partial order events

- ▷ $<$: precedence order (rep with \longrightarrow)
- ▷ $-\rightarrow$: event order.
- ▷ $< \cup -\rightarrow$: **total**.

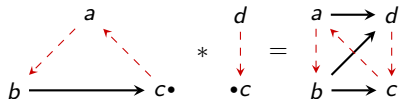
- Interfaces

Source/Target interfaces: S/T : $< -$ minimal/maximal.

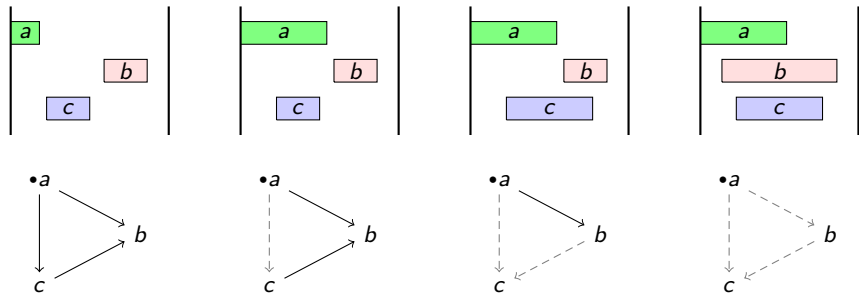
- Representation of events as interval

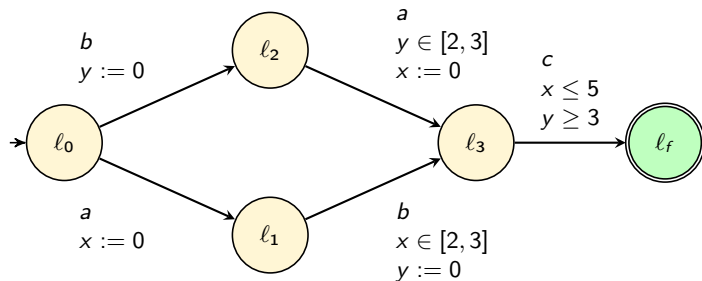


Example of operation: gluing



What about the time duration of events?





- HDA:

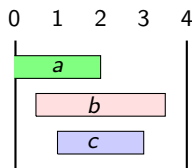
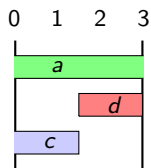
- ▷ Representation concurrency relation
- ▷ Extension of some properties of classic Automata

- Issues:

- ▷ No information about time duration of each events
- ▷ How to represent timing perturbation ?

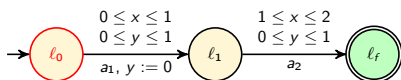
- Goals:

Extend the objects/operation/results from HDA to HDTA: adding information on the start/end dates of each event.

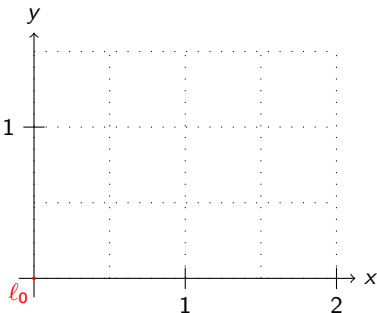


What about the robustness?

- Timed automaton \mathcal{A} :

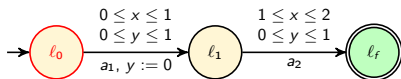


- Run with delay perturbations of at most $\delta = 0.2$

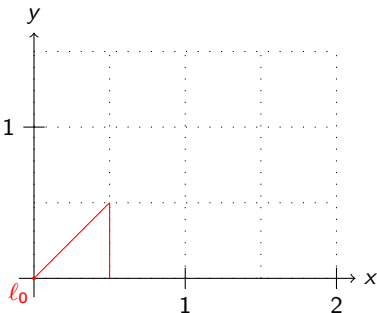


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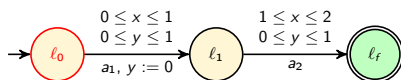


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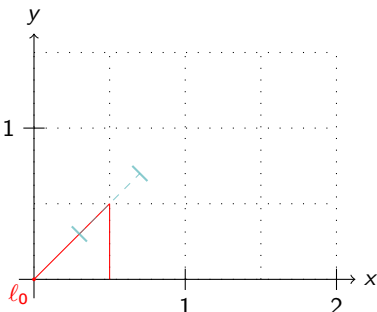


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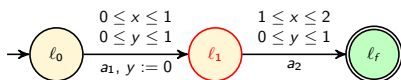


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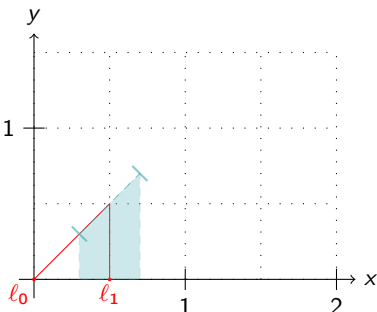


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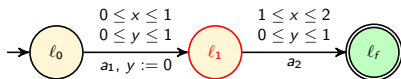


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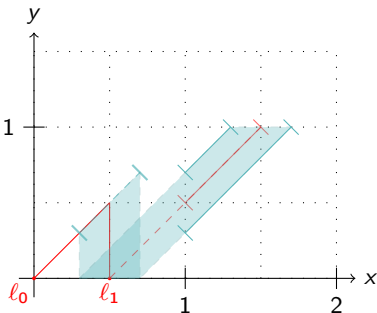


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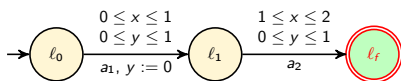


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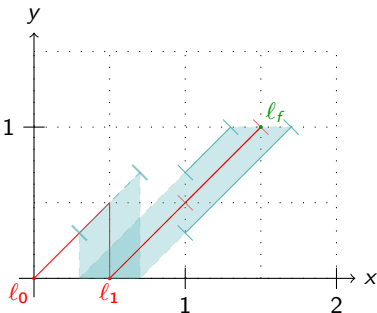


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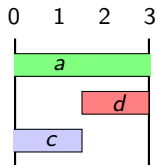
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- No timing perturbation: c and d are not in concurrency



- timing perturbation. Let us introduce a 0.1 delay on the end date of c :

