

Effective models in high dimensional unstable regimes

Some examples from machine learning and porous media

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High dimension, instability, correlations



Kinetic theory

- $N \approx 10^{11}$ stars, $6 \times N$ variables
- Microscopic instabilities creating tractable correlations

Learning

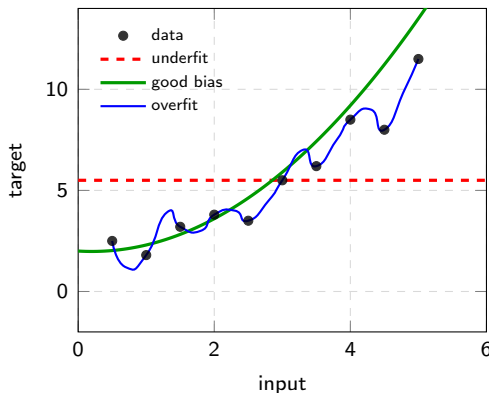
- high-dimensional correlated data and architectures
- unstable training procedures

What is the effect of the underlying instabilities on the effective model?

Overparametrisation and implicit regularization

#parameters $\gg$ #data

- Easy interpolation of the **training set**
- **Generalization:** good prediction on **unseen data**
- Many interpolating predictors
- Why this one rather than another?



We need a **bias / regularization** selecting the right interpolant.
This is the mechanism we want to capture in the effective dynamics.

Wide two-layer networks: the model

- **One-hidden-layer model:**

$$f_N(x) = \frac{1}{N} \sum_{i=1}^N \phi(x, \theta_i) = \int \phi(x, \theta) d\rho_N(\theta),$$

$$\rho_N = \frac{1}{N} \sum_{i=1}^N \delta_{\theta_i}$$

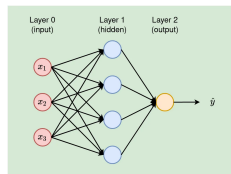
- θ_i : parameters of one neuron
- ρ_N : empirical distribution of parameters
- $\phi(x, \theta)$: response of one neuron to the input x
- **Training functional:**

$$\mathcal{F}(\rho) = \mathbb{E}_{(x,y)} [\ell(y, f_\rho(x))]$$

$$f_\rho(x) = \int \phi(x, \theta) d\rho(\theta)$$

$\ell(y, f_\rho(x))$ = prediction error against the label y

Overparametrization becomes a problem on probability measures.



Wide two-layer networks: the mean-field picture

- Gradient descent on the neurons:

$$\theta_i^{(k+1)} = \theta_i^{(k)} - \eta N \nabla_{\theta_i} \mathcal{F}(\rho_N^{(k)})$$

- Small learning rate, many neurons:

$$\eta \ll 1, \quad t = k\eta, \quad N \rightarrow \infty \quad \Longrightarrow \quad \partial_t \rho - \operatorname{div}_{\theta} \left(\rho \nabla_{\theta} \frac{\partial \mathcal{F}}{\partial \rho}(\rho) \right) = 0$$

- Specific choice for $\mathcal{F}$:

$$\mathcal{F}(\rho) = \frac{1}{2} \int_{\Omega} g * (\rho - \mu) d(\rho - \mu) \quad \text{Maximum mean discrepancy}$$

Small η : mean-field / Wasserstein gradient flow

Large η : unstable dynamics $\Rightarrow$ modified effective model

The stable case: small learning rate

collaboration with Matthew Rosenzweig

The framework: a mean-field equation

Consider the small learning-rate regime $\eta \rightarrow 0$.

- $t \geq 0$: training time, ρ : parameter density, $\mu \in \mathcal{P}(\mathbb{T}^d)$: target distribution.

$$\begin{cases} \partial_t \rho - \operatorname{div}(\rho \nabla g * (\rho - \mu)) = 0, \\ \rho|_{t=0} = \rho_0. \end{cases} \quad (1)$$

- This is the Wasserstein gradient flow of the Coulomb MMD:

$$\operatorname{MMD}^2(\rho, \mu) = \frac{1}{2} \int_{\mathbb{T}^d} g * (\rho - \mu) d(\rho - \mu).$$

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- g : the Coulomb kernel

$$-\Delta g = \delta_0 - 1.$$

- **Stable regime:** instability is encoded in the singular kernel but does not modify the effective model.

Well-posedness and asymptotic behavior

- **Trade-off:** large-time behavior **and** stability of the flow.
- **Previous results:**¹ global well-posedness in Hölder spaces and convergence if

$$\inf_{\mathbb{T}^d} \rho_0 > 0, \quad \inf_{\mathbb{T}^d} \mu > 0.$$

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Theorem (ACDC, M.Rosenzweig)

Let $\rho_0 \in \mathcal{P}(\mathbb{T}^d)$ and $\mu \in \mathcal{P} \cap L^\infty(\mathbb{T}^d)$ with

$$\lambda := \inf_{\mathbb{T}^d} \mu > 0.$$

Then the Coulomb MMD flow admits weak solutions that satisfy $\rho_t \in L^\infty(\mathbb{T}^d)$ for all $t > 0$ and

$$\text{MMD}^2(\rho_t, \mu) \leq C_s e^{-2\lambda(t-s)} \text{MMD}^2(\rho_s, \mu) \quad (t \geq s > 0).$$

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Use of a *defect* Polyak-Lojasiewicz inequality.

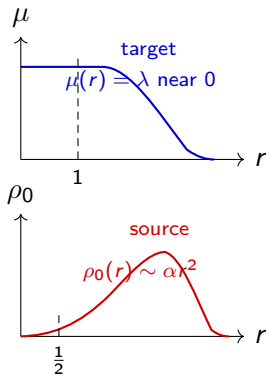
Regularity can deteriorate

- Hölder regularity is propagated, but the norm may grow.

Theorem (ACDC, M.Rosenzweig)

There exist smooth compactly supported radial densities ρ_0, μ on $\mathbb{R}^d$ such that, for every $\beta \in (0, 1]$ and $t \geq 0$,

$$[\rho_t]_{C^{0,\beta}} \geq c_\beta e^{\beta\lambda \frac{d+2}{2d}t}, \quad \lambda = \mu(0).$$



The unstable case: large learning rate

Stability condition for explicit Euler discretization

Gradient descent:

$$\theta^{(k+1)} = \theta^{(k)} - \eta \nabla E(\theta^{(k)}).$$

Explicit Euler scheme for the **gradient flow** at time $t = k\eta$:

$$\frac{d\theta}{dt} = -\nabla E(\theta), \quad \theta(k\eta) \approx \theta^{(k)} \quad \text{as } \eta \ll 1.$$

Stability condition for explicit Euler discretization

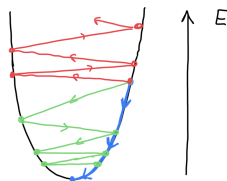
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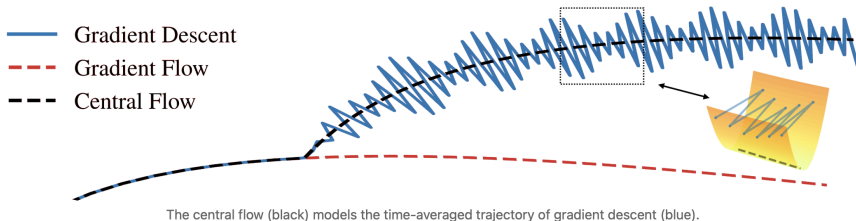
- **Issue:** large $\eta \implies$ **instability**.
- **Key quantities:** eigenvalues λ_i of $\nabla^2 E(\theta)$.



- $\eta \lambda_i \in (2, \infty) \Leftrightarrow$ **unstable** oscillations along eigenvector of λ_i ,
 $\eta \lambda_i \in (1, 2) \Leftrightarrow$ **stable** oscillations along eigenvector of λ_i .

Related work

- **Goal:** modify the effective model.
- Cohen, Damian et al.: **Central Flow**.²



²Jeremy Cohen et al. "Gradient Descent on Neural Networks Typically Occurs at the Edge of Stability". In: *International Conference on Learning Representations*. 2021. URL: <https://openreview.net/forum?id=jh-rTtvkGeM>;
Jeremy Cohen et al. "Understanding Optimization in Deep Learning with Central Flows". In: *The Thirteenth International Conference on Learning Representations*. 2025. URL: <https://openreview.net/forum?id=sIE2rI3ZPs>

Related work

Idea: ansatz $\theta^{(k)} = \bar{\theta}^{(k)} + \sqrt{\eta} \delta \theta^{(k)}$.

$$\frac{d\bar{\theta}}{dt} = -\nabla E(\bar{\theta}) - \frac{1}{2}\eta \nabla \nabla^2 E(\bar{\theta}) : \Sigma, \quad \Sigma = \mathbb{E}(\delta \theta \delta \theta^T), \quad \bar{\theta}(k\eta) \approx \theta^{(k)}.$$

- **Stabilization** : escape “too unstable” minima.
- **Central Flow**: structural assumptions on the covariance matrix Σ :
fast relaxation of oscillations

$$\text{Im } \Sigma \subset \ker(2/\eta - \nabla^2 E(\bar{\theta})).$$

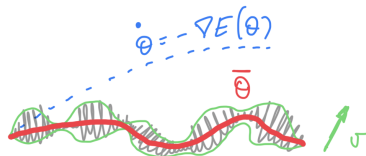
- Strength: strong empirical evidence.
- Limitation: strong assumptions on oscillations; hard to analyse rigorously.

A second-order model³

Unpredictable oscillations given $\bar{\theta}$: second-order model.

$$\begin{aligned}\frac{d\bar{\theta}}{dt} &= -\eta \nabla E(\bar{\theta}) - \frac{1}{2} \eta^2 \nabla \nabla^2 E(\bar{\theta}) : \Sigma, \\ \frac{d\Sigma}{dt} &= -\eta (\nabla^2 E(\bar{\theta}) \Sigma + \Sigma \nabla^2 E(\bar{\theta})) + \eta^2 \nabla^2 E(\bar{\theta}) \Sigma \nabla^2 E(\bar{\theta}).\end{aligned}$$

- Σ : covariance envelope of the fast oscillations.
- Same macroscopic time scale for Σ and $\bar{\theta}$.
- No hard-coded relaxation constraint on Σ .



³Antonin Chodron de Courcel. Gradient descent at the Edge of Stability: free energy model and kinetic description of the two-layer network. 2026. arXiv: 2606.05326 [cs.LG]. URL: <https://arxiv.org/abs/2606.05326>.

Free energy and low-curvature regime

$$H = \nabla^2 E(\bar{\theta}), \quad F(\bar{\theta}, \Sigma) = E(\bar{\theta}) + \frac{\eta}{2} H : \Sigma.$$

- If $\|H\|_{L^\infty} \leq 2/\eta$, then

$$\frac{d}{dt} F(\bar{\theta}_t, \Sigma_t) = -\eta \|\nabla_{\bar{\theta}} F(\bar{\theta}_t, \Sigma_t)\|^2 \leq 0.$$

- Persistent oscillations are critical points of F :

$$\nabla_{\bar{\theta}} F = 0, \quad H\Sigma + \Sigma H - \eta H\Sigma H = 0.$$

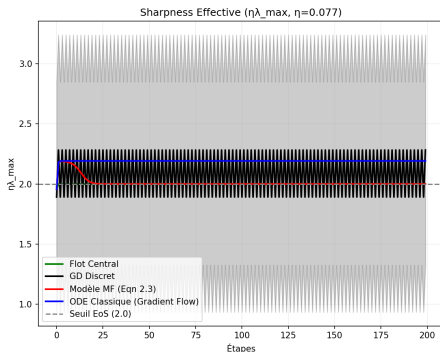
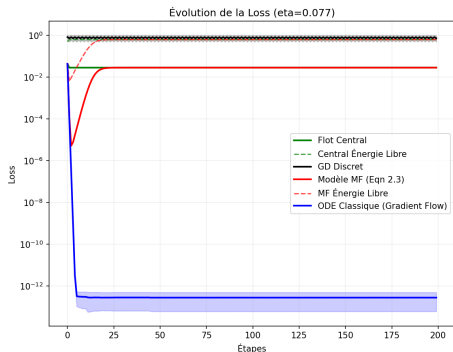
- **Low-curvature / flat landscape:** if $E \mapsto \lambda E$ with $\lambda \ll 1$ and $\tau = t/(\eta\lambda)$,

$$\frac{d\Sigma}{d\tau} = -(\Sigma H + H\Sigma).$$

- Rank is preserved, hence $\Sigma = v \otimes v$ and $\frac{dv}{d\tau} = -Hv$.

Numerical simulations

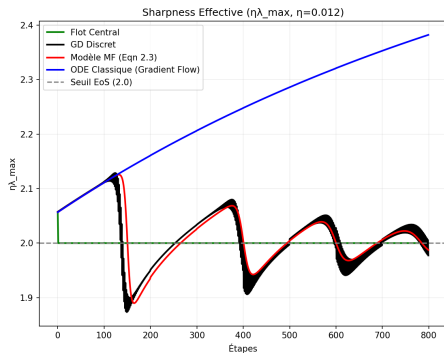
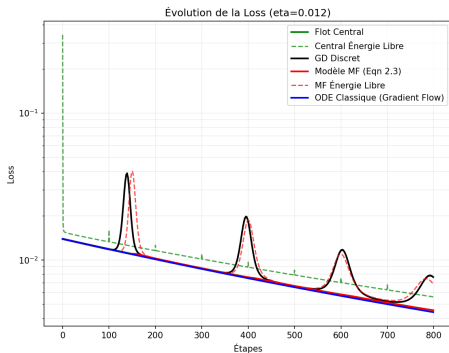
Matrix factorization



Matrix factorization, $\eta = 0.077$, 10 seeds, 200 steps.

Numerical simulations

MLP on CIFAR-10

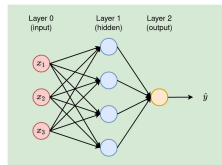


MLP on CIFAR-10, $n = 500$, MSE loss, $\eta = 0.012$, 800 steps.

Wide networks as mean-field models

- One-hidden-layer model:

$$f_N(x) = \frac{1}{N} \sum_{i=1}^N \phi(x, \theta_i) = \int \phi(x, \theta) d\rho_N(\theta).$$



- Gradient-flow training⁴:

$$\mathcal{F}(\rho) = \mathbb{E} \left[\ell \left(y, \int \phi d\rho \right) \right], \quad \frac{\partial \rho}{\partial t} - \operatorname{div}_{\theta} (\rho \nabla_{\theta} \frac{\partial \mathcal{F}}{\partial \rho}(\rho)) = 0.$$

- Special case:

$$\mathcal{F}(\rho) = \frac{1}{2} \int g * (\rho - \mu) d(\rho - \mu), \quad \frac{\partial \rho}{\partial t} - \operatorname{div}_{\theta} (\rho \nabla g * (\rho - \mu)) = 0.$$

⁴Lénaïc Chizat and Francis Bach. "On the Global Convergence of Gradient Descent for Over-parameterized Models using Optimal Transport". In: *Advances in Neural Information Processing Systems 31 (NeurIPS)*. 2018, pp. 3040–3050. URL: <http://papers.nips.cc/paper/7567-on-the-global-convergence-of-gradient-descent-for-over-parameterized-models-using-optimal-transport>; Song Mei, Andrea Montanari, and Phan-Minh Nguyen. "A mean field view of the landscape of two-layer neural networks". In: *Proceedings of the National Academy of Sciences* 115.33 (2018), E7665–E7671. DOI: 10.1073/pnas.1806579115. URL: <https://www.pnas.org/doi/abs/10.1073/pnas.1806579115>.

Connection with our model

$\bar{\theta} = (\bar{\theta}_1, \dots, \bar{\theta}_N) \in (\mathbb{R}^d)^N$ and $\Sigma = (\Sigma_{i,j})_{1 \leq i,j \leq N} \in (\mathbb{R}^{d \times d})^{N \times N}$.

$$\begin{aligned}\frac{d\bar{\theta}_i}{dt} &= -N \nabla_{\bar{\theta}_i} \mathcal{F}(\rho_N) - \frac{1}{2} \eta N \nabla_{\bar{\theta}_i} \nabla^2 \mathcal{F}(\rho_N) : \Sigma, \\ \frac{d\Sigma}{dt} &= -N \nabla^2 \mathcal{F}(\rho_N) \Sigma - N \Sigma \nabla^2 \mathcal{F}(\rho_N) + \underbrace{\eta N \nabla^2 \mathcal{F}(\rho_N) \Sigma \nabla^2 \mathcal{F}(\rho_N)}_{O(1/N)}.\end{aligned}$$

Equation for $f(\bar{\theta}, \mathbf{v})$:

$$\begin{aligned}\frac{\partial f}{\partial t} - \operatorname{div}_{\bar{\theta}}(f \nabla \mathbf{g} * (\rho - \mu)) - \frac{1}{2} \eta \operatorname{div}_{\bar{\theta}}(f \nabla_{\bar{\theta}}(\nabla^2 \mathbf{g} : \mathbf{v} \otimes \mathbf{v}) * (f - \mu)) \\ - \operatorname{div}_{\mathbf{v}}(f(\nabla^2 \mathbf{g} \mathbf{v}) * (f - \mu)) = 0,\end{aligned}$$

where $\rho := \int f \, d\mathbf{v}$ and $\mathbf{v} \in \mathbb{R}^{d \times r}$ represents the r oscillation directions⁵.

In the mean-field limit, the quadratic term in Σ disappears: we recover precisely the low-curvature / Bures regime.

⁵assumed $O(1)$.

Connection with our model

$$\begin{aligned} \frac{\partial f}{\partial t} - \operatorname{div}_{\bar{\theta}}(f \nabla g * (\rho - \mu)) - \frac{1}{2} \eta \operatorname{div}_{\bar{\theta}}(f \nabla_{\bar{\theta}}(\nabla^2 g : v \otimes v) * (f - \mu)) \\ - \operatorname{div}_v(f(\nabla^2 g v) * (f - \mu)) = 0, \end{aligned}$$

- Weighted Wasserstein-2 gradient flow, with metric $d\theta^2 + \eta dv^2$, for the free energy

$$\mathcal{F}(f) = \frac{1}{2} \int g * (\rho - \mu) d(\rho - \mu) + \frac{\eta}{4} \int \nabla^2 g : (v \otimes v) * (f - \mu) d(f - \mu).$$

- $\eta \propto N \implies$ **strong particle correlations** : mean-field may be insufficient.

Theorem for the kinetic PDE⁶

$$\begin{aligned} \frac{\partial f}{\partial t} - \operatorname{div}_{\bar{\theta}}(f \nabla g * (\rho - \mu)) - \frac{1}{2} \eta \operatorname{div}_{\bar{\theta}}(f \nabla_{\bar{\theta}}(\nabla^2 g : v \otimes v) * (f - \mu)) \\ - \operatorname{div}_v(f(\nabla^2 g v) * (f - \mu)) = 0, \quad (2) \end{aligned}$$

Theorem (ACDC)

Let $g \in C_b^{3,1}$, $f_0 \in \mathcal{P}_2(\mathbb{R}^d \times \mathbb{R}^{d \times r})$ compactly supported in the v variable and $\mu \in \mathcal{P}(\mathbb{R}^d)$.

For all $T > 0$, there exists a unique, compactly supported in v , solution $f \in C([0, T], \mathcal{P}_2(\mathbb{R}^d \times \mathbb{R}^{d \times r}))$ to (2), which furthermore satisfies

$$\frac{d}{dt} \mathcal{F}(f) + \int_{\mathbb{R}^d \times \mathbb{R}^{d \times r}} \left(\left| \nabla_{\theta} \frac{\delta \mathcal{F}}{\delta f} \right|^2 + \frac{1}{\eta} \left| \nabla_v \frac{\delta \mathcal{F}}{\delta f} \right|^2 \right) df \leq 0. \quad (3)$$

Finally, if g is smooth enough, the regularity of f_0 is propagated in time.

⁶Antonin Chodron de Courcel. Gradient descent at the Edge of Stability: free energy model and kinetic description of the two-layer network. 2026. arXiv: 2606.05326 [cs.LG]. URL: <https://arxiv.org/abs/2606.05326>.

Singularities and saturation effects in porous media

Framework

Nonlinear mobility

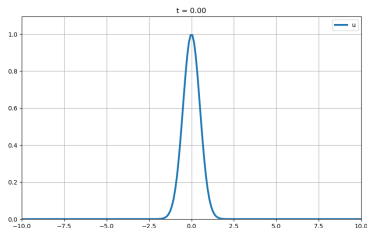
- Equations of the form:

$$\partial_t u - \operatorname{div}(u^m \nabla g * u) = 0, \quad \mu(u) = u^{m-1} \quad \text{nonlinear mobility.}$$

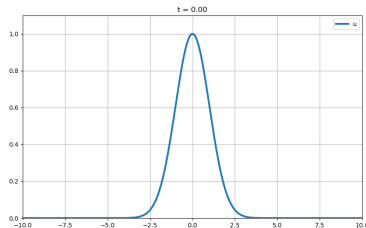
- Riesz interaction $g(x) \approx |x|^{-s}$, $s \in (0, d)$:

$$\partial_t u - \textcolor{red}{m} u^{\textcolor{red}{m}-1} \nabla g * u \cdot \nabla u + u^m (-\Delta)^{\frac{s-d+2}{2}} u = 0.$$

Slow diffusion $m \geq 1$



Fast diffusion $m < 1$



Singularity s

$m = 0$

$m = 1$

Porous-media
equation $s = d$

Super-Coulomb

Conditional L^∞ regularization
& infinite speed [Cho26b]

Coulomb $s = d - 2$

Sub-Coulomb

Long-time behavior, support speed [CE25]

BV estimates
[Cho25]

Mobility m

Bounded force

Bounded interactions

L^1 stability, entropy uniqueness,
BV estimates, convergence rates [Cho25]

Clogging and ultra-fast diffusion
Infinite propagation speed,
conditional regularization

Fast diffusion
Infinite propagation speed

Slow diffusion
Finite propagation speed

The Coulomb case

The radial case

- **Key issues:**
 - ▶ shocks and rarefaction waves.
 - ▶ support propagation.
- **Radial case⁷:** link with Hamilton-Jacobi equations:

$$k(t, s) := \int_0^s u(t, r) dr$$

solves

$$\partial_t k + (\partial_s k)^m k = 0.$$

⁷José A. Carrillo, David Gómez-Castro, and Juan Luis Vázquez. "A fast regularisation of a Newtonian vortex equation". In: *Annales de l'Institut Henri Poincaré C, Analyse Non Linéaire* 39.3 (2022), pp. 705–747. DOI: 10.4171/AIHPC/17; José A. Carrillo, David Gómez-Castro, and Juan Luis Vázquez. "Vortex formation for a non-local interaction model with Newtonian repulsion and superlinear mobility". In: *Advances in Nonlinear Analysis* 11.1 (2022), pp. 937–967. DOI: doi:10.1515/anona-2021-0231. URL: <https://doi.org/10.1515/anona-2021-0231>. 

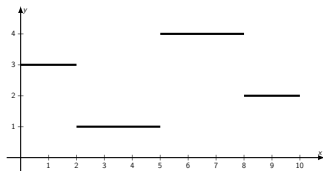
The non-radial Coulomb case⁸

- Compactness.
- Support analysis through decreasing rearrangement:

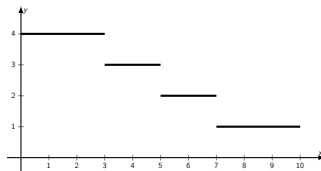
$$k(t, s) := \int_0^s u_*(t, \sigma) d\sigma,$$

where $u_*(t, \sigma) := \inf\{\xi : |\{u(t) > \xi\}| \leq \sigma\}$.

Original function $u(x)$

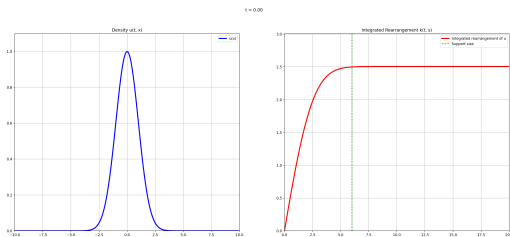


Decreasing rearrangement $u_*(x)$



- k is a viscosity subsolution of $\partial_t k + (\partial_s k)^m k = 0$.

⁸Antonin Chodron de Courcel and Charles Elbar. “On a repulsion model with Coulomb interaction and nonlinear mobility”. In: *arXiv:2510.16894* (2025).



Theorem (ACDC, C. Elbar)

Let $u_0 \in L^\infty(\mathbb{T}^d)$ be nonnegative and let $m \geq 1$. There exists an entropy solution u whose support grows instantly if the low-density layer of u_0 is sufficiently thin, i.e.

$$\frac{k(0, S_0) - k(0, s)}{(S_0 - s)^{\frac{m}{m-1}}} \gg 1 \text{ as } s \rightarrow S_0, \quad S_0 := |\text{supp } u_0|.$$

Conversely, if $u_0^{m-1} \in C^{0,1}$, then the support size remains constant for a positive waiting time.

References

- [CE25] Antonin Chodron de Courcel and Charles Elbar. “On a repulsion model with Coulomb interaction and nonlinear mobility”. In: *arXiv:2510.16894* (2025).
- [Cho25] Antonin Chodron de Courcel. “Well-posedness of multidimensional nonlocal conservation laws with nonlinear mobility and bounded force”. In: *arXiv:2512.13535* (2025).
- [Cho26a] Antonin Chodron de Courcel. *Gradient descent at the Edge of Stability: free energy model and kinetic description of the two-layer network*. 2026. *arXiv: 2606.05326 [cs.LG]*. URL: <https://arxiv.org/abs/2606.05326>.
- [Cho26b] Antonin Chodron de Courcel. “On Clogged and Fast Diffusions in Porous Media with Fractional Pressure”. In: *SIAM J. Math. Anal.* 58.2 (2026), pp. 1367–1390.
- [CR26] Antonin Chodron de Courcel and Matthew Rosenzweig. *About the Wasserstein gradient flow of the Coulomb discrepancy on $\mathbb{R}^d$ and $\mathbb{T}^d$* . 2026.

Thank you for your attention!