

Automatic Design of Multi-Objective Local Search Algorithms

Case Study on a bi-objective Permutation Flowshop Scheduling Problem

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Context

Metaheuristics: Highly Tunable Algorithms

Key Points

- ▶ Approximation algorithms for optimisation problems
- ▶ Few assumptions about the problem
- ▶ Many parameters and strategies

Performance

- ▶ Differs with the problem
- ▶ Differs with the instance
- ▶ Depends on its configuration (set of parameter values)

Context

Automatic Algorithm Configuration

Single-Objective Configuration

- ▶ Learn the optimal configuration on a training instance set
- ▶ irace [López-Ibáñez *et al.*, 2016], ParamILS [Hutter *et al.*, 2009],
SMAC [Hutter *et al.*, 2010], GGA++ [Ansótegui *et al.*, 2015], ...

Multi-Objective Configuration

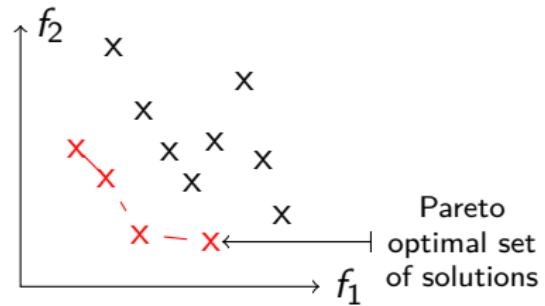
- ▶ MO-ParamILS [Blot *et al.*, LION 2016]
- ▶ Optimise multiple performance indicators

Context

Configuring Multi-Objective Algorithms

Performance Indicators

- ▶ Convergence
- ▶ Diversity
- ▶ Spread
- ▶ Size



Multi-Objective Configuration

- ▶ Configuring a MO algorithm is a MO problem [Blot et al., EMO 2017]

Motivation

Designing Efficient Multi-Objective Metaheuristics

Question

- ▶ How efficient is MO-AAC to design MO metaheuristics?

Case Study

- ▶ MO-ParamILS
- ▶ Multi-objective Local Search algorithms
- ▶ Bi-objective Permutation Flowshop Scheduling Problem

Case Study

MOLS: Multi-objective Local Search Algorithms

Key Points

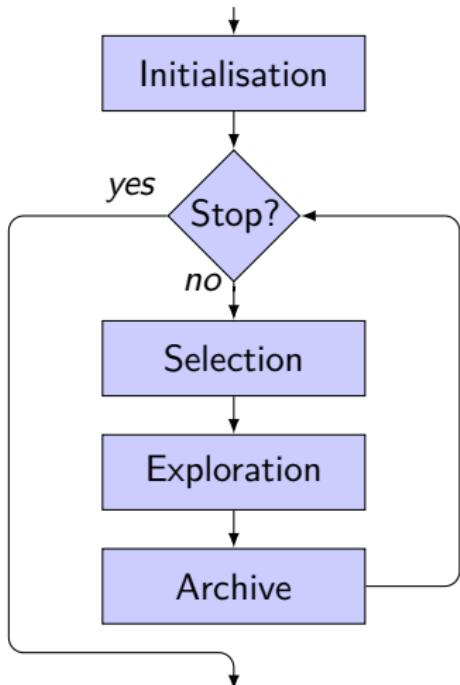
- ▶ Efficient metaheuristics
- ▶ Used on many problems (e.g., scheduling, routing, assignment)
- ▶ Many strategies and parameters

In the Literature

- ▶ Methods
 - ▶ Pareto Archived Evolution Strategy (PAES, 1999, 2000)
 - ▶ Pareto Local Search (PLS, 2001, 2004, 2011, 2012, 2015)
- ▶ Unifications
 - ▶ Stochastic Pareto Local Search (SPLS, 2012)
 - ▶ Dominance-based Multi-objective Local Search (DMLS, 2012)

Multi-Objective Local Search Algorithms

Simple Workflow



Example Parameters

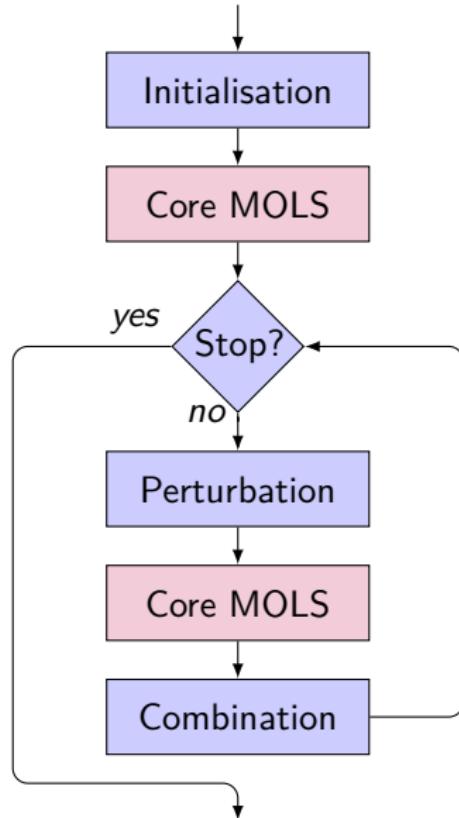
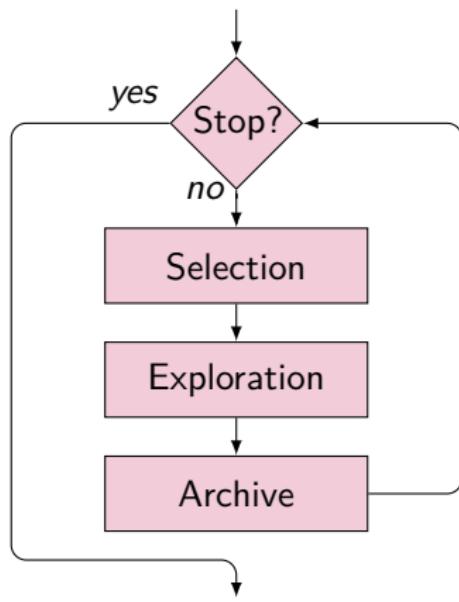
- ▶ Selection
 - ▶ Type and number of solutions
- ▶ Exploration
 - ▶ Neighbourhood
 - ▶ Reference point
 - ▶ Type and number of neighbours
- ▶ Archive
 - ▶ Archive size
 - ▶ Type of solutions

Multi-Objective Local Search Algorithms

Iterated Workflow

Iterated Local Search (ILS)

[Lourenço *et al.*, 2003]



MOLS Adaptability

Highly Configurable

- ▶ Initialisation
- ▶ Selection
- ▶ Exploration
- ▶ Archive
- ▶ Iteration
- ▶ Perturbation

Possible MOLS Parameters

Parameter	Type	Parameter values
initStrat	category	{rand, neh, ig}
selectStrat	category	{all, rand, newest, oldest}
selectSize	integer	1+
explorStrat	category	{all, imp, ndom, ... }
explorRef	category	{pick, arch}
explorSize	integer	1+
archiveStrat	category	{bounded, unbounded, ... }
archiveSize	integer	1+
iterationLength	integer	1+
iterationStagnation	integer	1+
perturbStrat	category	{restart, kick}
perturbSize	integer	1+
perturbStrength	integer	1+

Experimental Protocol

Goal: Compare MO-AAC Performance to Exhaustive Analysis

MO-ParamILS

- ▶ Training
- ▶ Validation
- ▶ Test

Exhaustive Analysis

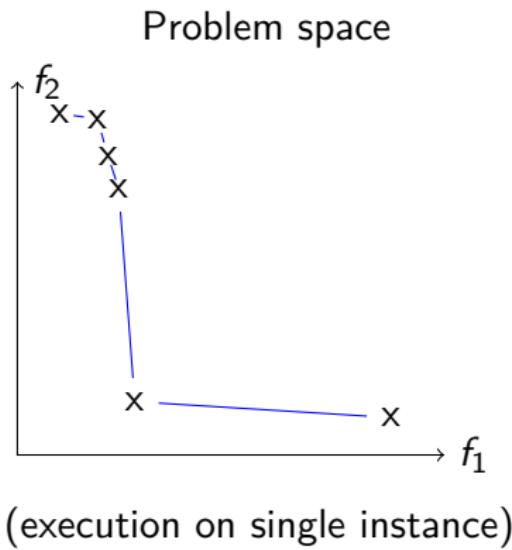
- ▶ Every possible configuration
- ▶ Only on the test set

MOLS

- ▶ Optimise:
 - ▶ Convergence
 - ▶ Distribution
- ▶ Minimise:
 - ▶ 1 - Hypervolume
 - ▶ Δ Spread

MO-ParamILS

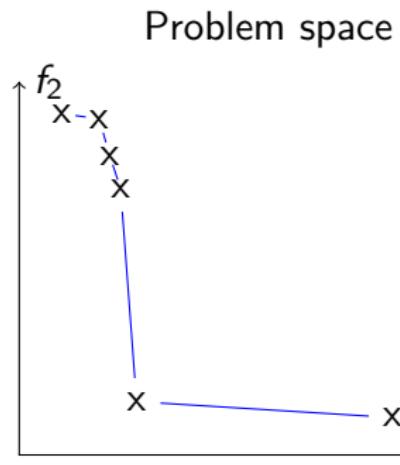
Training



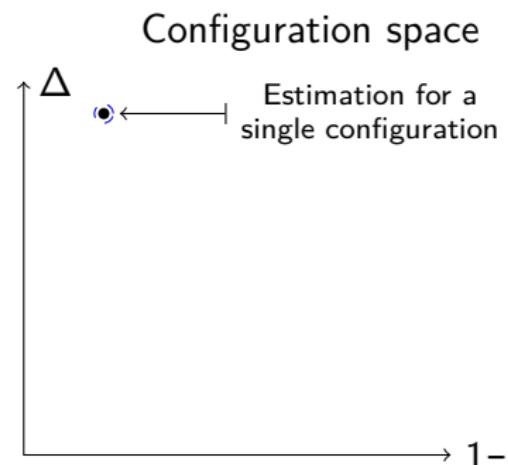
- ▶ For every configuration
 - ▶ multiple runs
 - ▶ multiple instances
- ▶ Average HV and Δ Spread over multiple runs

MO-ParamILS

Training



(execution on single instance)

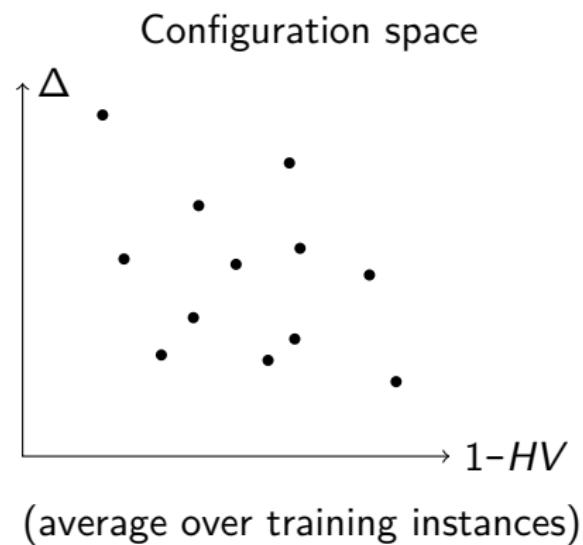


(average over training instances)

MO-ParamILS

Training

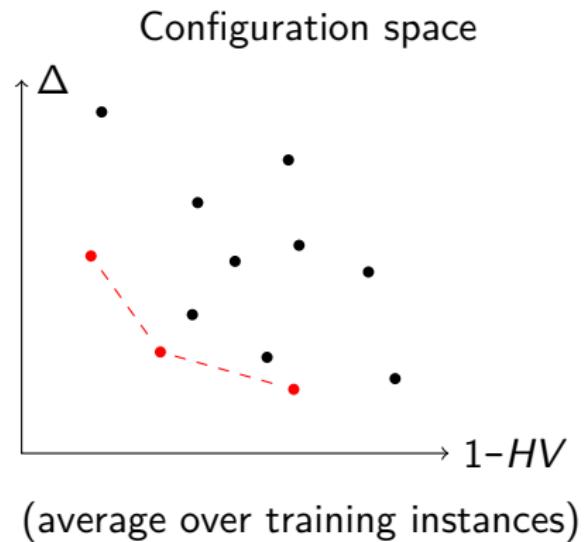
- ▶ iteratively investigates configurations
- ▶ refining quality estimations
- ▶ returns non-dominated
- ▶ shuffles training instances



MO-ParamILS

Training

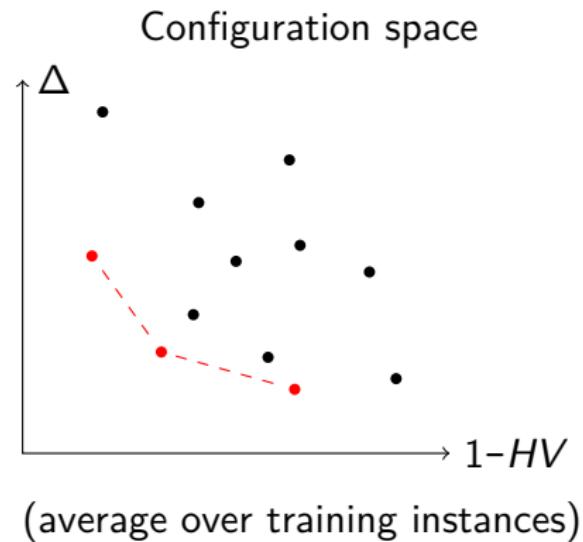
- ▶ iteratively investigates configurations
- ▶ refining quality estimations
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MO-ParamILS

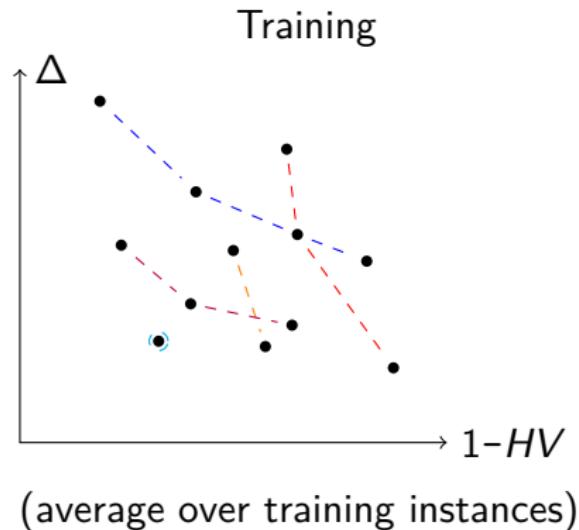
Training

- ▶ iteratively investigates configurations
- ▶ refining quality estimations
- ▶ returns **non-dominated**
- ▶ shuffles training instances



MO-ParamILS Protocol

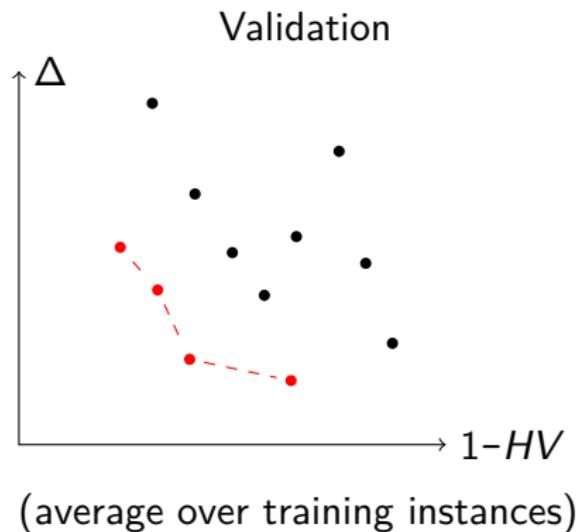
Training, Validation, Test



- ▶ Training
 - ▶ 30 training runs
 - ▶ different instance subsets
 - ▶ incomparable quality estimation
- ▶ Validation
 - ▶ all training configurations
 - ▶ all training instances

MO-ParamILS Protocol

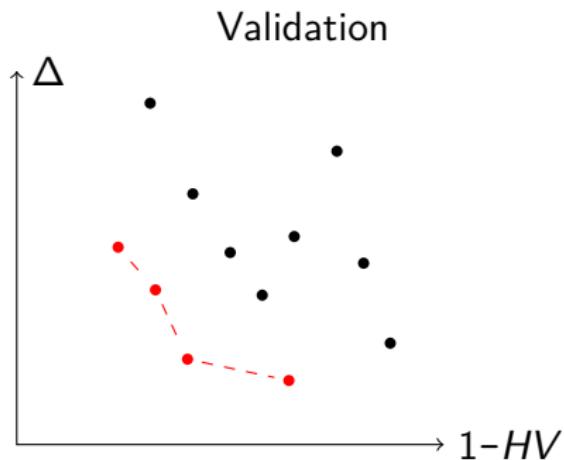
Training, Validation, Test



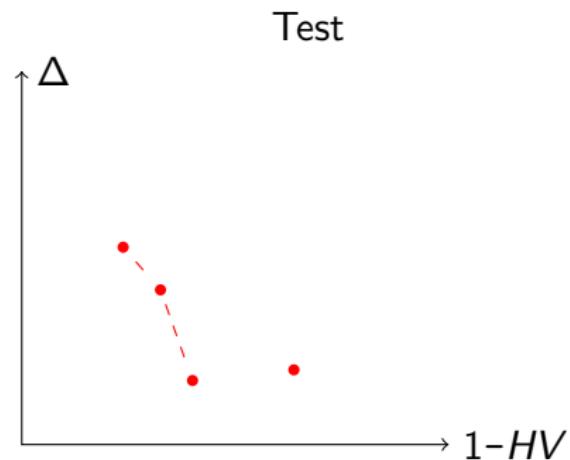
- ▶ Training
 - ▶ 30 training runs
 - ▶ different instance subsets
 - ▶ incomparable quality estimation
- ▶ Validation
 - ▶ all training configurations
 - ▶ all training instances

MO-ParamILS Protocol

Training, Validation, Test



(average over training instances)



(average over test instances)

Experimental Protocol

Summary

Permutation Flowshop Scheduling Problem

- ▶ Classical Taillard instances
- ▶ Bi-objective optimisation:
 - ▶ Makespan
 - ▶ Flowtime
- ▶ 3 scenarios:
 - ▶ 20-job instances
 - ▶ 50-job instances
 - ▶ 100-job instances

189 MOLS Configurations

Parameter	Parameter values
initStrat	{rand, neh, ig}
selectStrat	{all, rand, new, old}
selectSize	{1, 3}
explorStrat	{all, imp, ndom}
explorRef	{pick, arch}
explorSize	{1, 3}

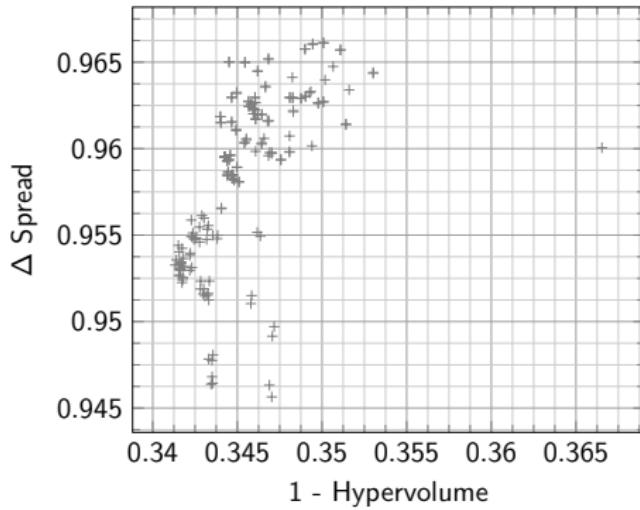
Total time

Approach	20-job	50-job	100-job
Training	36 min	90 min	3 hours
MO-AAC	2 days	7 days	15 days
Exhaustive	46 days	115 days	230 days

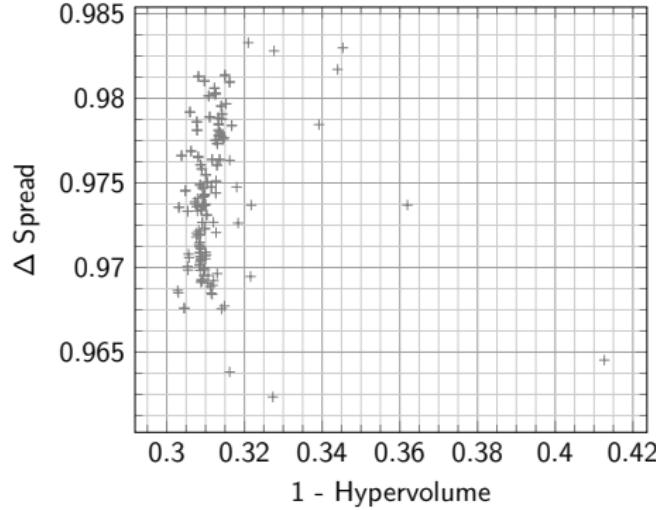
Results

Exhaustive analysis

PFSP Taillard instances – 50 jobs



PFSP Taillard instances – 100 jobs



Exploration Selection Strategies

► Δ all

► Δ all

► o imp

► ■ newest

► + ndom

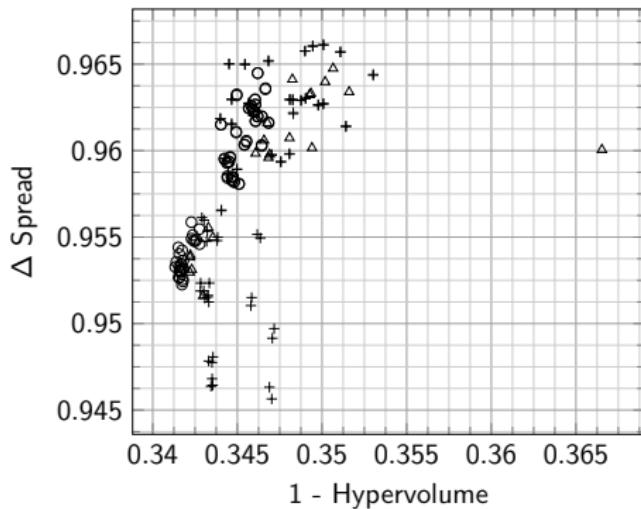
► □ oldest

► ▲ rand

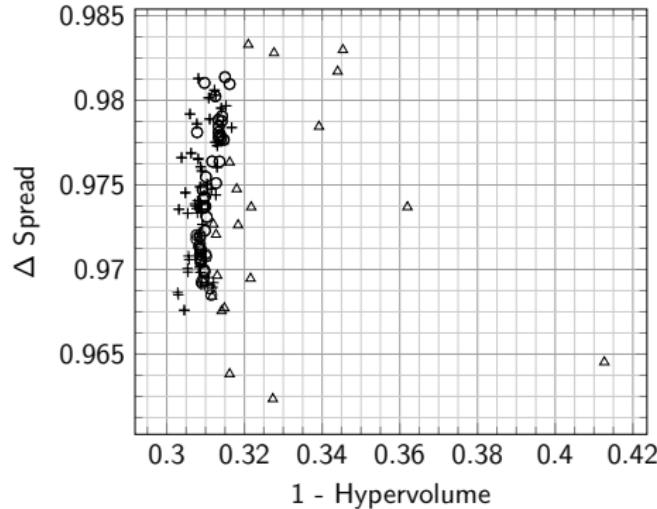
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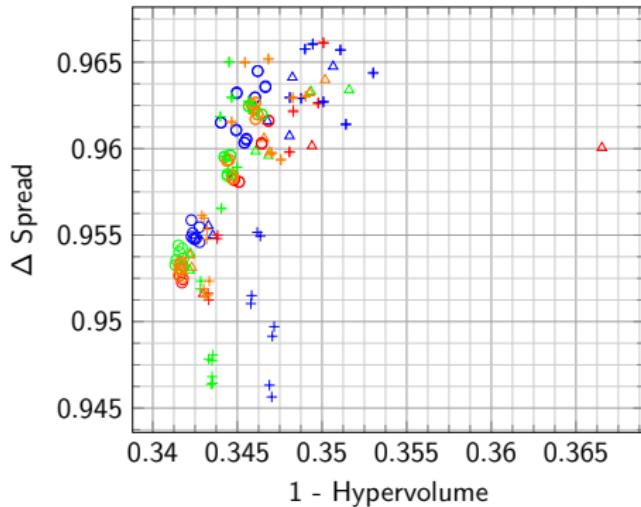
Exploration / Selection Strategies

- ▶ Δ all
- ▶ \circ imp
- ▶ $+$ ndom
- ▶ \blacksquare all
- ▶ \blacksquare newest
- ▶ \blacksquare oldest
- ▶ \blacksquare rand

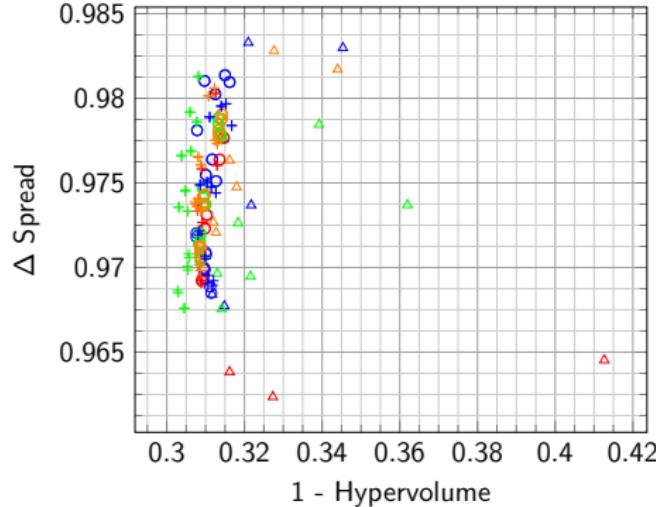
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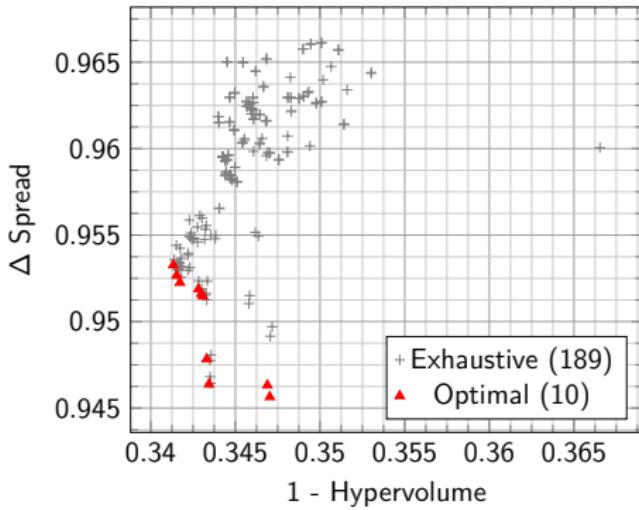
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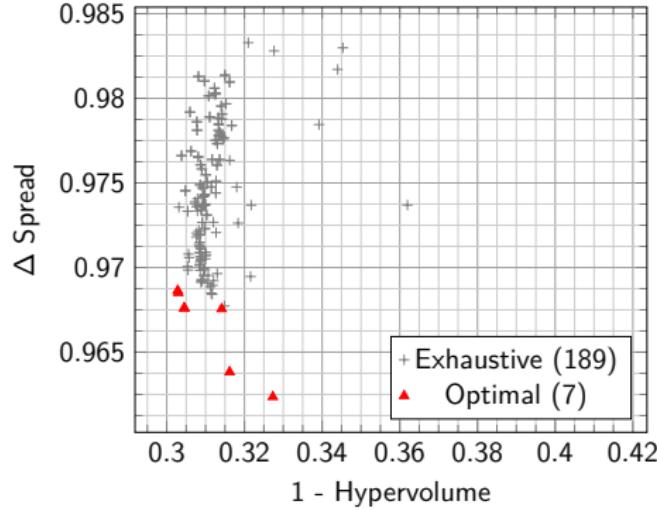
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Exploration Selection Strategies

► Δ all

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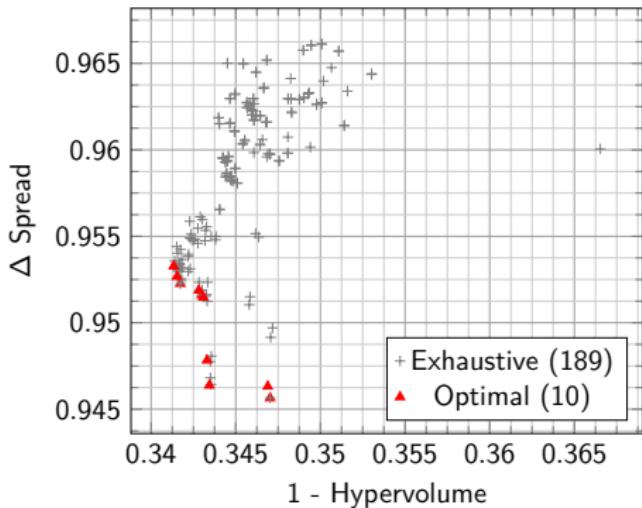
► □ oldest

► ▲ rand

Results

Multi-Objective Automatic Design

PFSP Taillard instances – 50 jobs



Optimal Configurations

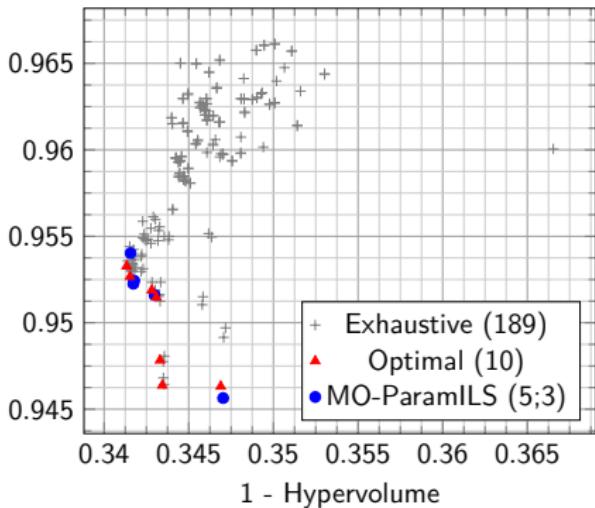
Init	Selection	Exploration			
ig	oldest	3	imp	3	pick
ig	rand	3	imp	3	pick
ig	all	-	imp	1	arch
ig	newest	3	ndom	3	pick
ig	all	-	all	-	arch
ig	rand	1	ndom	1	arch
ig	newest	3	ndom	3	arch
ig	newest	3	ndom	1	arch
ig	oldest	3	ndom	1	arch
ig	oldest	3	ndom	3	arch

Results

Multi-Objective Automatic Design

PFSP Taillard instances – 50 jobs

Δ Spread



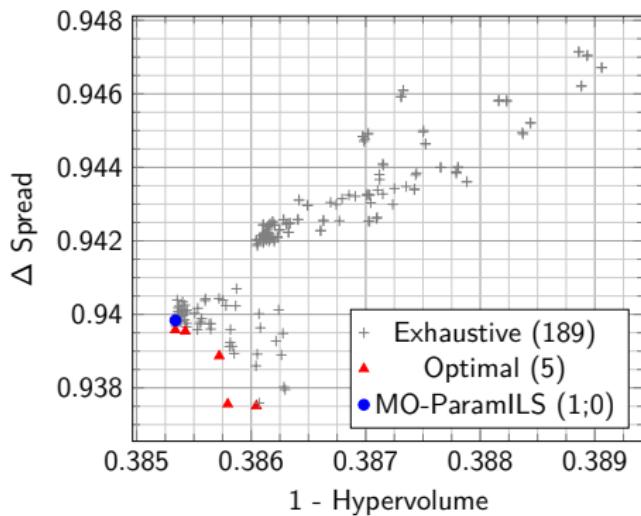
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ig	rand	3	imp	3	pick
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ig	newest	3	ndom	3	pick
ig	all	-	all	-	arch
ig	rand	1	ndom	1	arch
ig	newest	3	ndom	3	arch
ig	newest	3	ndom	1	arch
ig	oldest	3	ndom	1	arch
ig	oldest	3	ndom	3	arch

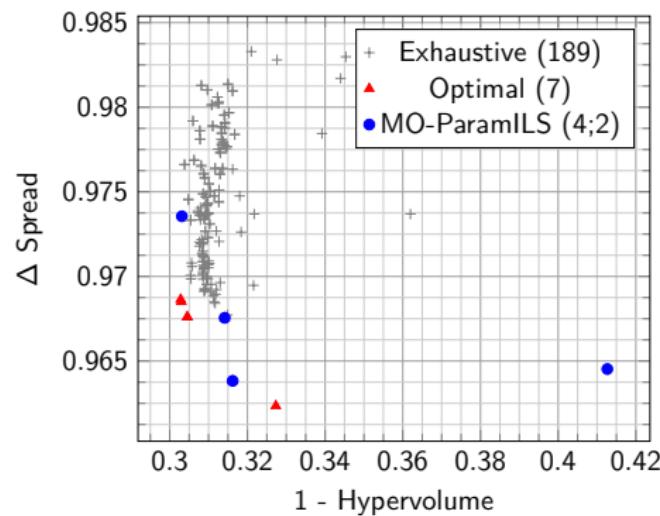
Results

Multi-Objective Automatic Design

PFSP Taillard instances – 20 jobs



PFSP Taillard instances – 100 jobs



Conclusion

Main Contribution

- ▶ Efficient Automatic design of MOLS algorithms for bi-objective PFSP

Perspectives

- ▶ Investigate automatic design on other problems
 - ▶ e.g., MO-TSP, MO-QAP
- ▶ Extends to other algorithms
 - ▶ e.g., GA, EA

Additional Contribution

- ▶ New MOLS generalisation

Wrap up

Take-home Message 1

- ▶ Configuring a MO algorithm is a MO problem [Blot *et al.*, EMO 2017]

Take-home Message 2

- ▶ Use configurable algorithms
 - ▶ Or expose tunable parameters
- ▶ Propose new components and strategies
- ▶ Design the final algorithm automatically