FOREST AUGMENTATION PROBLEM

Semester project under the supervision of Ola Svensson

Igor Martayan June 14, 2022



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• resilient: stay connected even if some nodes / edges fail

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- resilient: stay connected even if some nodes / edges fail
- affordable: minimize the cost of the network

k-edge-connectivity

For every pair (s, t), there are at least kedge-disjoint paths between s and t



example of 2-edge-connected graph

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most of these problems are NP-hard \rightarrow approximation algorithms



example of 2-edge-connected graph

- Graph augmentation: formulation, hardness, recent progress
- Matching augmentation: LP-based approximation algorithm

GRAPH AUGMENTATION PROBLEM

Graph augmentation

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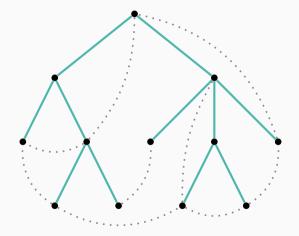
Graph augmentation

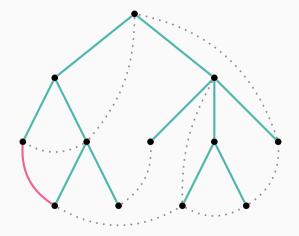
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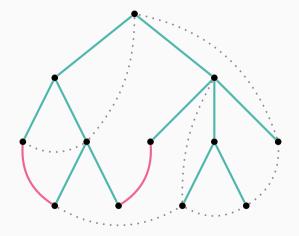
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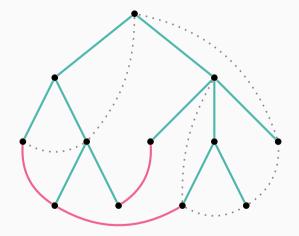
Weighted version

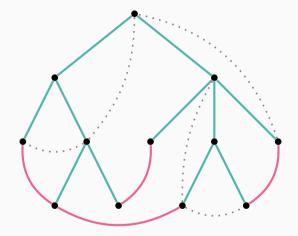
Input G = (V, E), $w : E \mapsto \mathbb{R}^+$, set of light edges $F \subseteq E$ Output Set of heavy edges $E' \subseteq E$ of min weight s.t. $(V, F \cup E')$ is 2-edge-connected











k-edge-connectivity, cut formulation

Every nontrivial cut has at least *k* edges

(special case of max-flow min-cut)

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Linear Program

$$\begin{split} \min \sum_{e \in E \setminus F} x_e \\ \sum_{e \in \delta(S)} x_e \geq 2 \quad \forall \varnothing \subsetneq S \subsetneq V \\ x_e \in \{0,1\} \quad \forall e \in E \end{split}$$

x_e indicates whether e is selected

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Relaxed Linear Program

$$\begin{split} \min \sum_{e \in E \setminus F} x_e \\ \sum_{e \in \delta(S)} x_e \geq 2 \quad \forall \varnothing \subsetneq S \subsetneq V \\ 0 \leq x \leq 1 \quad \forall e \in E \end{split}$$

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NP optimization problems that have a poly-time approximation algorithm with a constant approximation ratio

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Theorem (Kortsarz & al. 2004)

Tree Augmentation is APX-hard

 $\exists \varepsilon$ s.t. approximating TAP with ratio $1 + \varepsilon$ is NP-hard

Weighted Tree Augmentation

• [Traub & al. 2021] $1 + \ln 2 + \varepsilon$ (Relative Greedy) Weighted Tree Augmentation

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- [Traub & al. 2022] $1.5 + \varepsilon$ (Local Search)

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Forest Augmentation [Grandoni & al. 2022] < 2 (Reduction to path augmentation) Approximating Matching Augmentation [Bamas, Drygala, Svensson, 2022] A Simple LP-Based Approximation Algorithm for the Matching Augmentation Problem

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- main result: better-than-2 approximation for MAP
- $\cdot\,$ using only cut-LP and a DFS tree

 $\min \sum_{e \in E \setminus M} x_e$ $\sum_{e \in \delta(S)} x_e \ge 2 \quad \forall \varnothing \subsetneq S \subsetneq V$ $0 \le x \le 1 \quad \forall e \in E$

Algorithm 1: LP-based approximation algorithm for MAP

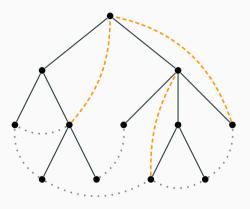
Input: A graph G = (V, E) and a matching $M \subseteq E$.

- $x^* \leftarrow \text{optimal extreme point solution to } LP(G, M)$
- $G' \leftarrow (V, \operatorname{Support}(x^*))$
- $T \leftarrow \mathsf{LIGHTDFS}(G', M) / / \text{depth-first-search tree prioritizing light edges}$
- $y^{*} \leftarrow \text{optimal extreme point solution to } LP(\mathit{G}',\mathit{T})$
- $A \leftarrow \text{Support}(y^*)$

return $T \cup A$

WHY ARE WE INTERESTED IN A DFS TREE?

- after building a DFS tree, the remaining edges are up-links
- up-link: one endpoint is an ancestor of the other



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For every square submatrix M of A, det $M \in \{-1, 0, 1\}$

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Theorem

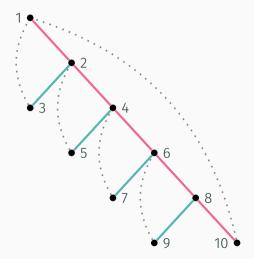
If $A \in \mathbb{R}^{m \times n}$ is totally unimodular and $b \in \mathbb{Z}^m$, then the extreme point solutions of

$$Ax \ge b$$
$$x \in [0,1]^n$$

are integral

WHY SHOULD WE RESTRICT THE DFS TREE TO THE SUPPORT?

IF WE DID NOT RESTRICT THE DFS TREE TO THE SUPPORT



WHERE DOES THE BETTER-THAN-2 RATIO COME FROM?

Suppose
$$\forall e, x_e^* \in \left\{0, \frac{1}{2}, 1\right\}$$

• cost of the DFS tree: cost(T) = n - 1 - |M|

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- "overcost" of T:

$$\operatorname{cost}(T) - x^*(T \setminus M) = \sum_{e \in T \setminus M} \underbrace{1 - x_e^*}_{\leq \frac{1}{2}}$$
$$\leq \frac{n - 1 - |M|}{2}$$
$$\leq \frac{x^*(E \setminus M)}{2}$$

- + cost of the DFS tree: $\cot(T) = n 1 |M|$
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• since x^* is feasible for LP(G', T),

$$y^*(E \setminus T) \le x^*(E \setminus T)$$

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• total cost:

$$\operatorname{cost}(T) + y^*(E \setminus T) \le x^*(T \setminus M) + \frac{x^*(E \setminus M)}{2} + x^*(E \setminus T) = \frac{3}{2}x^*(E \setminus M)$$

Each fractional edge is associated to a tight constraint

$$\mathcal{S} = \{ S \subsetneq V; x^*(\delta(S)) = 2 \}$$

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 $\mathcal{F} \subseteq 2^V$ is laminar: for every sets $A, B \in \mathcal{F}$, either $A \subseteq B, B \subseteq A$ or $A \cap B = \emptyset$

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Cardinality of a laminar family

If |V| = n and \mathcal{F} is laminar, then $|\mathcal{F}| \leq 2n - 1$

$$1_{\delta(A \cap B)} + 1_{\delta(A \cup B)} \le 1_{\delta(A)} + 1_{\delta(B)}$$



Uncrossing property

If $S, T \in \mathcal{S}$ are not disjoint, then $S \cap T \in \mathcal{S}$ and $S \cup T \in \mathcal{S}$

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$$\operatorname{span}(\mathcal{F}) = \operatorname{span}\left\{1_{\delta(S)}; S \in \mathcal{F}\right\}$$

Theorem

Let \mathcal{F} be the maximal laminar subfamily of \mathcal{S} , then $\operatorname{span}(\mathcal{F}) = \operatorname{span}(\mathcal{S})$

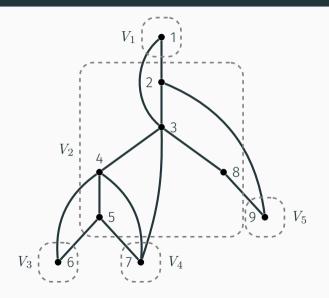
- forest augmentation is still a very active problem
- despite its hardness, the approximations keep improving
- analyzing it involves many elegant constructions

Next directions:

- \cdot refine the approximation ratio
- use other techniques such as tree carving
- extend to path augmentation

APPENDIX

TREE CARVING



DFS TREE WITH PATHS

