

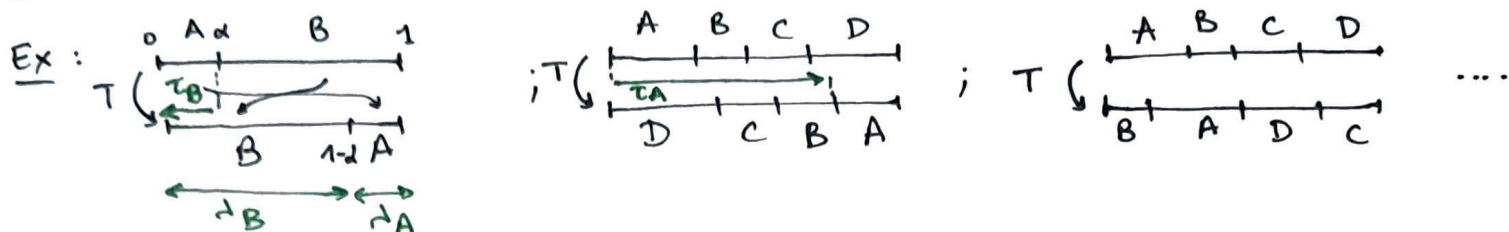
Interval Exchange Transformations

Magali Jay
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I. Definition

Let $I \subset \mathbb{R}$ be an interval. An interval exchange transformation (IET) on I is a bijection $T: I \setminus D_1 \rightarrow I \setminus D_2$ where:

- D_1 and D_2 are finite (of the same cardinality)
- and on each connected component of $I \setminus D_1$, T is a translation



There are two classical ways to describe an IET:

- Give the tuples $\{\beta_i\} = D_1$ (including the endpoints of I) and $\{\tau_i\}$ of translation lengths (= length of the translation on each c.c. of $I \setminus D_1$)

or

- Give the tuple $\{d_i\}_{i \in [1, d]}$ of lengths: the length of each c.c. of $I \setminus D_1$ and the bijection $\pi: [1, d] \rightarrow [1, d]$ of how T permutes the c.c. of $I \setminus D_1$

Note that the order in $\{\tau_i\}$ and in $\{d_i\}$ is important!

~~the~~

Ex: $\{\beta_i\} = \{0, \alpha, 1\}$ corresponds to the first example above

$$\{\tau_i\} = \{1-\alpha, -\alpha\}$$

$$\{d_i\} = \{\alpha, 1-\alpha\}$$

$$\pi = (1 \ 2)$$

We will mostly use (if not only) the second way, with a slight change:

We consider an alphabet A of d symbols with which we label the c.c.'s.

We give a pair of bijections (π_0, π_1) , $\pi_i: A \rightarrow [1, d]$ s.t. $\pi = \pi_1 \circ \pi_0^{-1}$

Notation:
$$\pi = \begin{pmatrix} \pi_0^{-1}(1) & \dots & \pi_0^{-1}(d) \\ \pi_1^{-1}(1) & \dots & \pi_1^{-1}(d) \end{pmatrix}$$

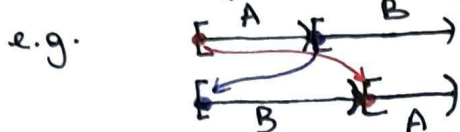
Giving (π_0, π_1) (and $\{d_i\}$) is redundant: the product $\pi = \pi_1 \circ \pi_0^{-1}$ (and $\{d_i\}$) is enough; but this is convenient (for the notation and for other tools that we will see later).

Ex: $\pi_0: \begin{matrix} A \rightarrow 1 \\ B \rightarrow 2 \end{matrix}$; $\pi_1: \begin{matrix} A \rightarrow 2 \\ B \rightarrow 1 \end{matrix}$; $\pi = \begin{pmatrix} A & B \\ B & A \end{pmatrix}$; $\pi = \begin{pmatrix} A & B & C & D \\ D & C & B & A \end{pmatrix}$; $\pi = \begin{pmatrix} A & B & C & D \\ B & A & D & C \end{pmatrix}$
permutations corresponding to the above examples

Rmk: To get a dynamical system, we need to be able to iterate the transformation T , which requires that the ~~subset~~ codomain of T is the same as (or at least included in) the domain of T .

We can:

1. Take segments that are open on the right, closed on the left so that we define T everywhere on $I = [a, b]$



or

2. Remove the backward orbit of each point in D_1
 ~~forward~~ D_2 \rightarrow get $I \setminus \Delta$

Δ is countable (in particular $\text{leb}_{\mathbb{R}}(\Delta) = 0$)

Explanation: T is not defined on D_1 , if x is such that $T(x) \in D_1$ then we can define $T(x)$ but not $T^2(x)$ so we remove x .

But then $y = T^{-1}(x)$ (assume it is defined) has again a finite well defined orbit $T(y) (= x)$, $T^2(y) (= T(x))$ and $T^3(y)$ is not def.

This is why we remove y , and, inductively, all backward orbits of D_1 . Denote $D_1^\infty = \bigcup_{n \in \mathbb{N}} T^{-n}(D_1)$.

Now we have $T: I \setminus D_1^\infty \rightarrow I \setminus D_2 \setminus D_1^\infty$ and we can iterate

By For the sake of symmetry we take $T: I \setminus \Delta \rightarrow I \setminus \Delta$

$$\text{with } \Delta = \bigcup_{n \in \mathbb{N}} T^{-n}(D_1) \cup \bigcup_{n \in \mathbb{N}} T^n(D_2)$$

II. From a translation surface to an IET

Proposition: Let S be a translation surface, and φ_t its vertical flow.

Let $I \subset S$ be an interval transverse to φ_t .

Then, the first return of φ_t to I defines an IET on I .

$$T: I \rightarrow I \quad \text{where } t_x = \min \{ t > 0 \mid \varphi_t(x) \in I \}$$

$$x \mapsto \varphi_{t_x}(x)$$

T might be not defined (if t_x is not finite). We will show that it is almost everywhere defined using the

Poincaré recurrence theorem

Let (X, μ) be a measured space and $T: X \rightarrow X$ be a μ -preserving map.

Let $A \subset X$ be a measurable set.

$$(\text{=} \forall A \text{ measurable set, } \mu(T^{-1}(A)) = \mu(A))$$

For almost every $x \in A$: $\forall N \in \mathbb{N}, \exists n \geq N$ s.t. $T^n(x) \in A$.

Proof of Poincaré recurrence theorem:

We have

$$\{x \in X \mid \forall N \in \mathbb{N}, \exists n \geq N, T^n(x) \in A\} = \bigcap_{N \in \mathbb{N}} \left(\bigcup_{n \geq N} T^{-n}(A) \right) =: B_N$$

We want to show that $\mu(A \setminus \bigcap_{N \in \mathbb{N}} B_N) = 0$

Note that (1) $B_{N+1} \subset B_N \subset B_0$

(2) $B_{N+1} = T^{-1}(B_N)$ so $\mu(B_{N+1}) \stackrel{\uparrow}{=} \mu(B_N) \stackrel{\uparrow}{=} \mu(B_0)$

We have:

$$\begin{aligned} \mu(A \setminus \bigcap_{N \in \mathbb{N}} B_N) &= \mu\left(\bigcup_{N \in \mathbb{N}} A \setminus B_N\right) \stackrel{\uparrow}{=} \mu\left(\bigcup_{N \in \mathbb{N}} B_0 \setminus B_N\right) \stackrel{\uparrow}{\leq} \mu\left(\bigcup_{N \in \mathbb{N}} B_0 \setminus B_N\right) \\ &\stackrel{\uparrow}{=} \mu\left(\bigcup_{N \in \mathbb{N}} B_0 \setminus B_N\right) \stackrel{\uparrow}{\leq} \sum_{N \in \mathbb{N}} \mu(B_0 \setminus B_N) \\ &= \sum_{N \in \mathbb{N}} (\mu(B_0) - \mu(B_N)) \stackrel{\uparrow}{=} \sum_{N \in \mathbb{N}} (\mu(B_0) - \mu(B_0)) \\ &= 0 \end{aligned}$$

induction
hypothesis of the thm
because (1)
because (2)
□

Remark: It works as well for continuous dynamical system.
(e.g. translation flow φ_t)
for almost every $x \in A$, $\forall T_0 > 0, \exists t > T_0$ st. $\varphi_t(x) \in A$